

Preliminary on-orbit Results on FengYun-4A Image Navigation and Registration



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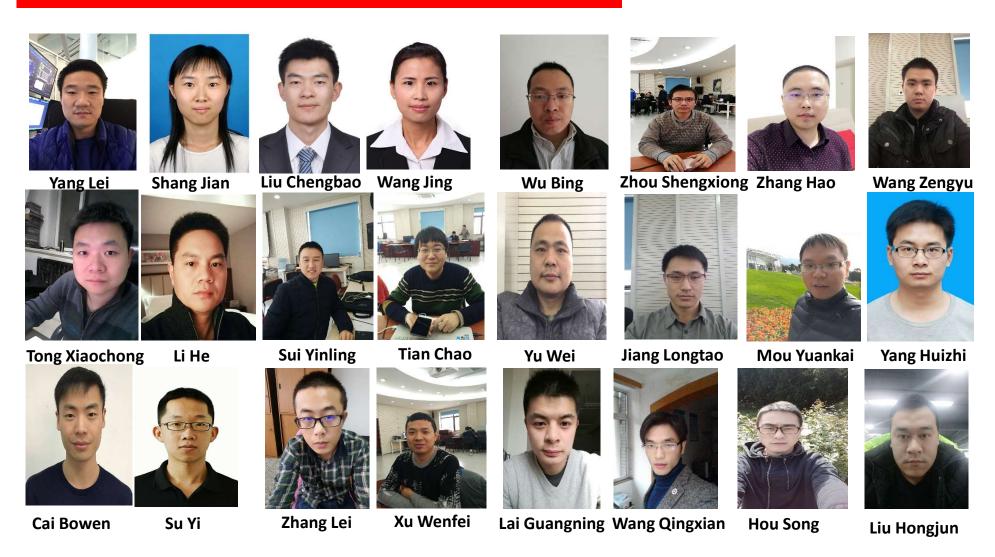


June 2017, IMAPP/CSPP 2017, University of Wisconsin-Madison, USA



Fengyun-4 Image Navigation and Registration

— Ground Segment



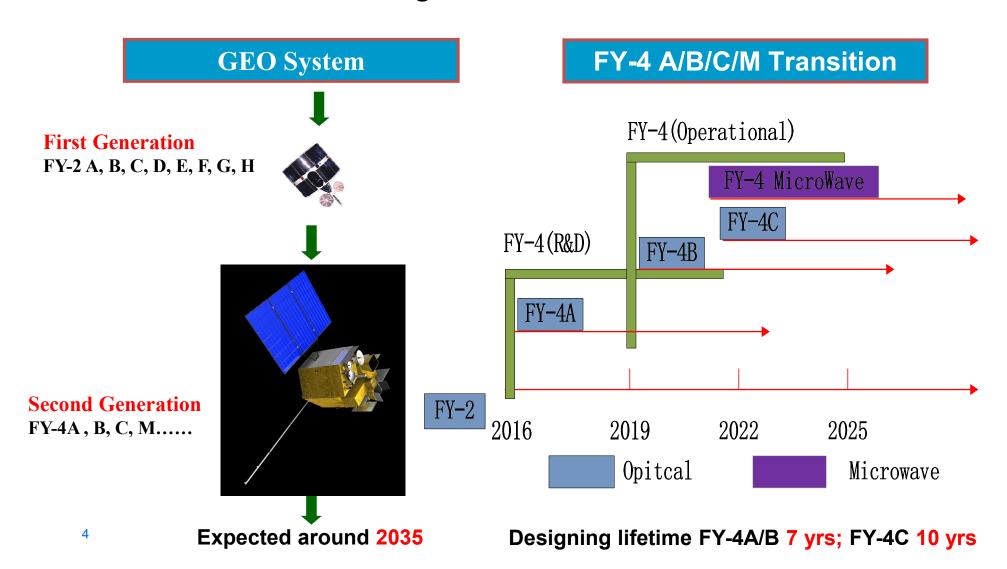
We are young!

Outline

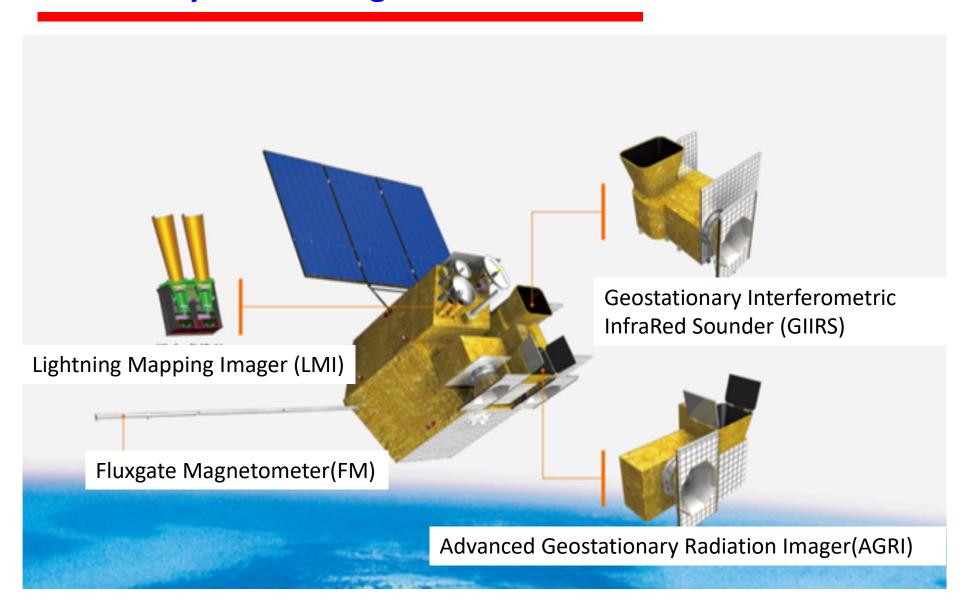
- 1. Brief History of China Geostationary Meteorological Satellites
- 2. Fengyun-4A Payloads Configuration
- 3. Fengyun-4A Image navigation and Registration(for 3 payloads) and preliminary on-orbit results
- 4. Conclusions

1. Brief History of China Geostationary Meteorological Satellites

FengYun GEO Satellites



2. FY-4A Payloads Configuration



FY-4A Important Dates

- □ Launched December 11, 2016
- □ Positioned on 99.5E above the equator and named with FY-4A -- December 17 2016
- □ Flipped to improve the calibration performance--March 20, 2017
- □Shifted from 99.5E to 104.7E -- May 18-25, 2017

Evolution from FY-2 to FY-4

- Platform transition from spin stabilization to 3-axis stabilization
 - Higher observation efficiency
 - Flexible area scanning mode
- Advanced radiation imager: AGRI
 - Channels: 5->14 bands
 - Full disk temporal resolution: 30->15min
 - Spatial resolution: 1.25Km->500m
- Interferometric Infrared Sounder, GIIRS new capability!
 - High spectrum resolution to enable better atmosphere T&H retrieval
- Lighting imager, LMI new capability!

Great Challenges have been brought to Fengyun-4 Navigation and Registration.

Great Challenges to Fengyun-4 Navigation and Registration System

Benefits



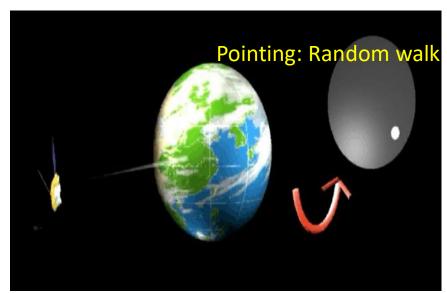
Great Challenges



- 1. Simultaneous observation: Imager and Sounder in one platform
- 2. Viewing efficiency of the imager
- 3. Favorite the radiometry accuracy
- 4. Favorite the ability of flexible viewing

- Pointing stability
 - 1 Platform itself stability(sun pressure, minor shake, liquid shake etc.)
 - 2 Imager's and Souder's mirrors influences

2. Thermal Gradient



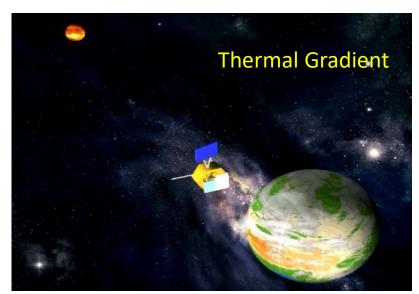
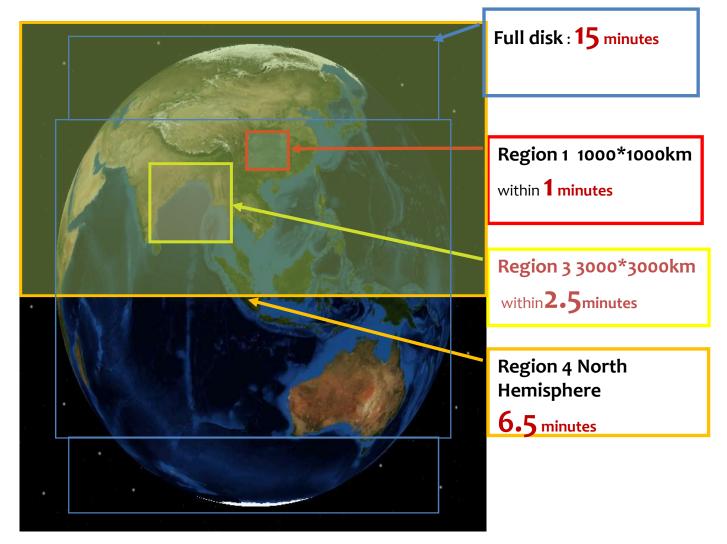


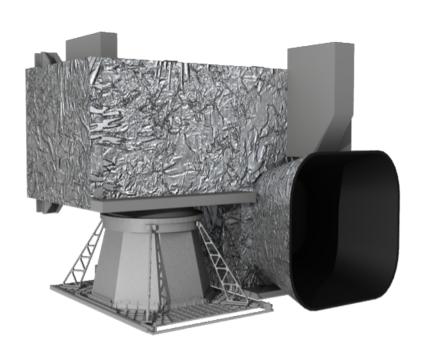
Figure 1. Platform Stability and thermal gradient

Fengyun-4 Observation Capability

- Continuous Full Disk
 - 15 minute Full Disk
- Flex Mode
 - 1 min 1000*1000km
 - 2.5min 3000*3000km
 - 6.5min north hemisphere
- Star observation, deep space/blackbody observation, earth observation are included.

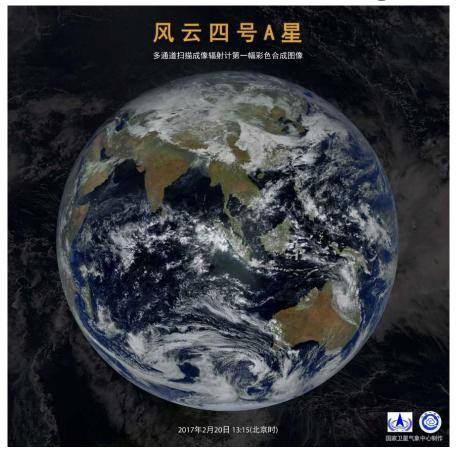


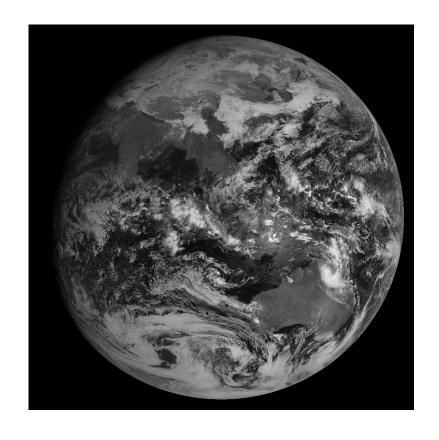
Fengyun-4 AGRI



- ➤ Mass: 306kg
- ➤ Number of Channels: 14(6 vis/near IR channels, 2 Middle IR, 2 water vapor channels and 4 LWIRs)
- Spatial Resolution: vis/near IR 0.5 ~ 1 km, IR 2~4km
- > Full disk scanning: 15min.
- Regional scanning time:: 1min. (1000kmx1000km)
- > SNR>3@1%, NEdeltaT0.2K

First FY-4/AGRI image released February 20





FY-4A AGRI VIS 20170220_0315 (UTC, Positioned on 99.5E)

FY-2G VIS 20170220_0300 (UTC, Positioned on 105E)

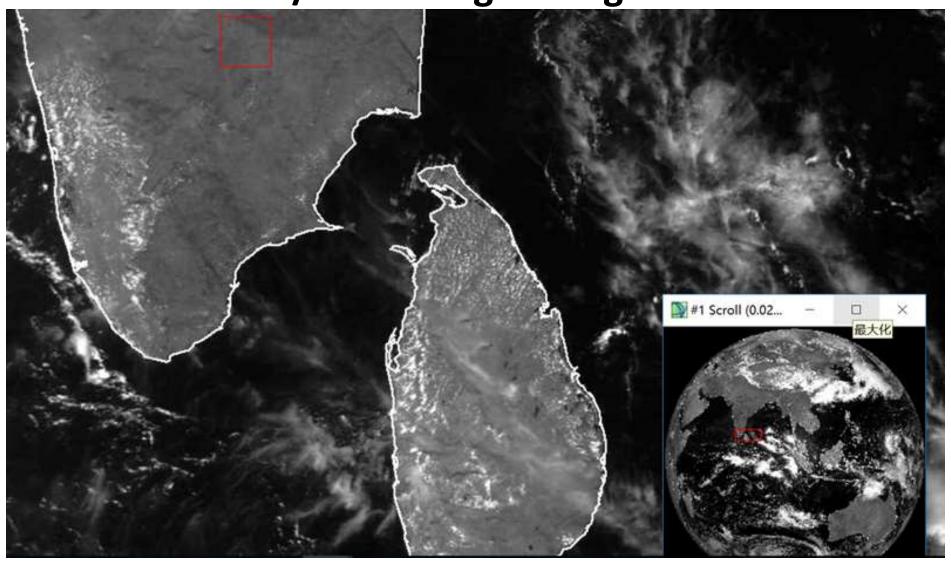
FY-4 vs FY-2 on February 20, 2017

FY-4/AGRI Animation



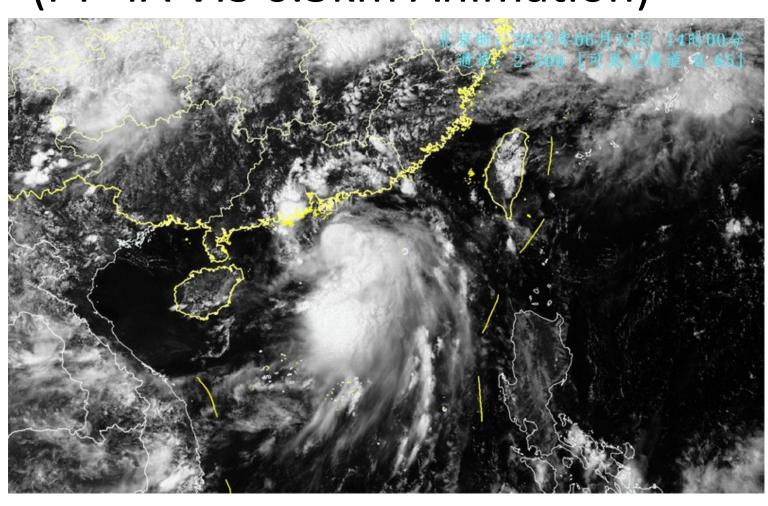
January 22nd 2017 FY-4/AGRI

FY-4/AGRI Image Navigation

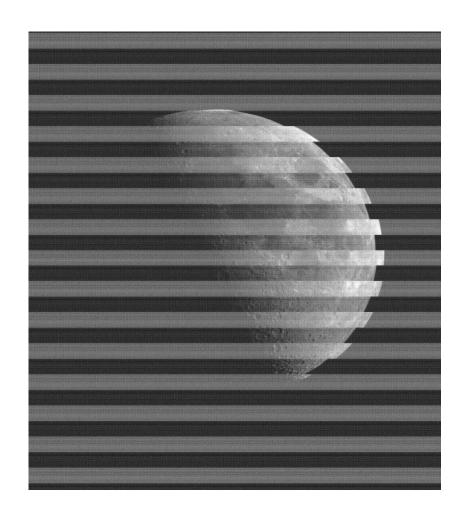


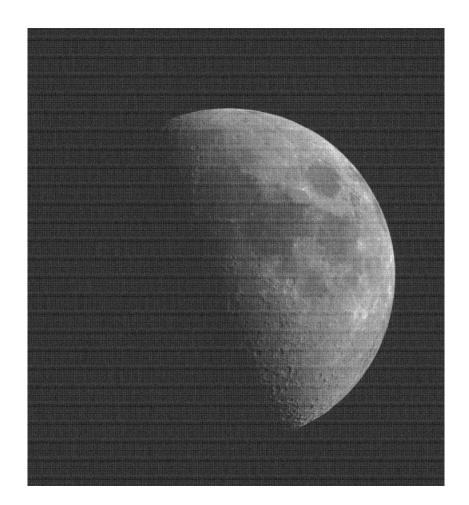
southern Indian subcontinent 201704110500 UTC 0.75~0.90um

"Merbok"—The 2017's first typhoon to land in China on June 22, 2017 (FY-4A VIS 0.5km Animation)



FY-4/AGRI Sees the Moon

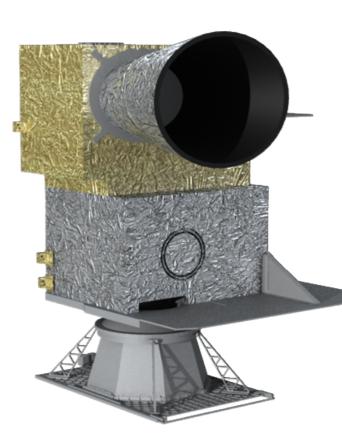




Moon registration and image motion compensation 20170601225751_CH2

FY-4/AGRI Image Navigation

Fengyun-4 GIIRS



- ➤ Mass: 315 kg
- Size: 1353.5mm(long)×2179.9mm(width)×1549mm(height)
- > Channel:

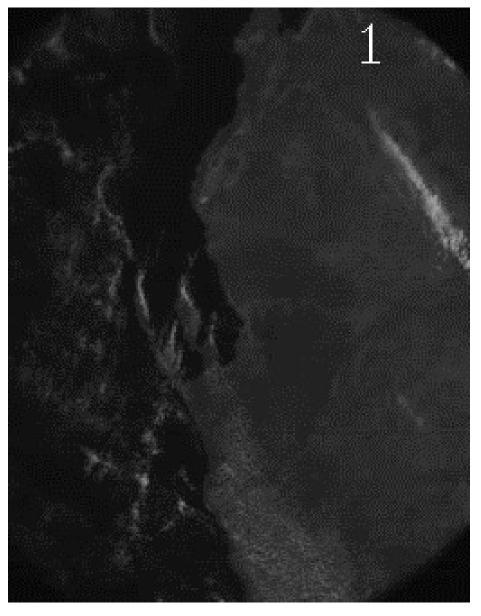
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LWIR:700-1130cm<sup>-1</sup> (8.85-14.29µm)
MWIR: 1650-2250cm<sup>-1</sup> (4.44-6.06µm)
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- ➤ Spectral resolution: 0.625cm⁻¹
- > The number of channels: 1650
- Spatial resolution: 16km
- Temporal resolution:

```
768km×960km (30min.)
4480km×5000km (60min.)
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- Radiation Cal Accu.: 1.5K
- Spectral Cal. Accu.: 10ppm
- For CMOS: 2km@ssp(star/landmark observation and cloud detection)

FY-4/GIIRS—Pointing Stability



The pointing variation is less than 0.05 IR pixel during 16 frames of sounding, which is very helpful for getting sounding profiles.

20170322041500

FY-4/GIIRS—image navigation accuracy

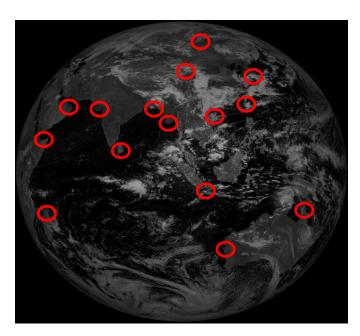


Fig.1 Landmarks used for FY-4/GIIRS Image Navigation Evaluation

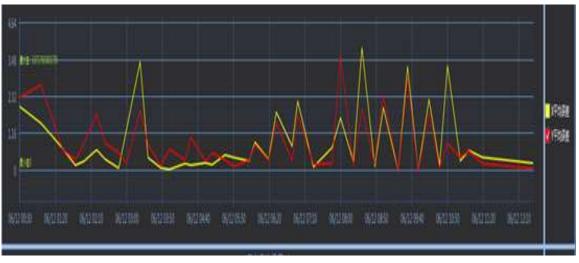


Fig.2 FY-4/GIIRS CMOS Landmark matching results (mean value less than 0.5 IR pixel)

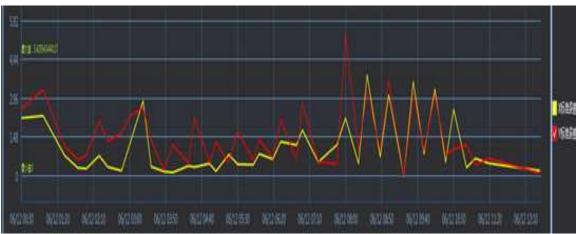


Fig.3 FY-4/GIIRS CMOS Landmark matching results(std)

FY-4 Lightning Mapping Imager (LMI) Image navigation

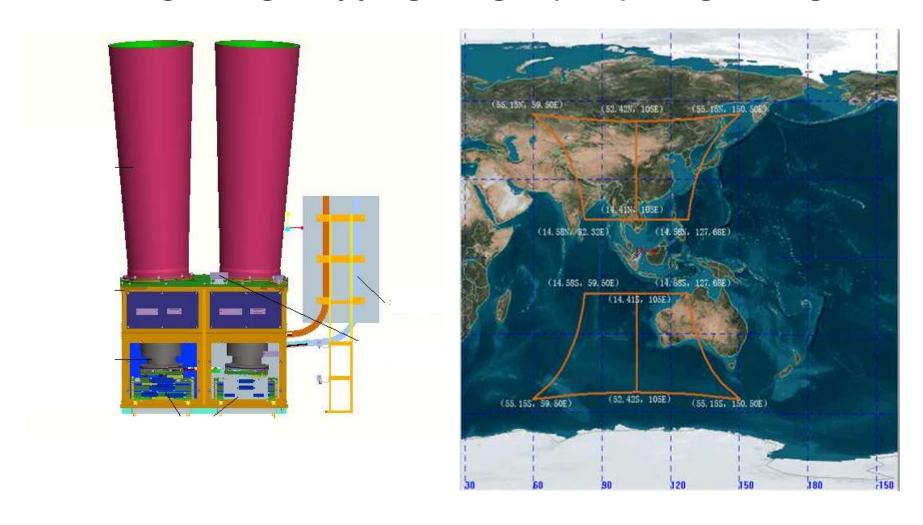
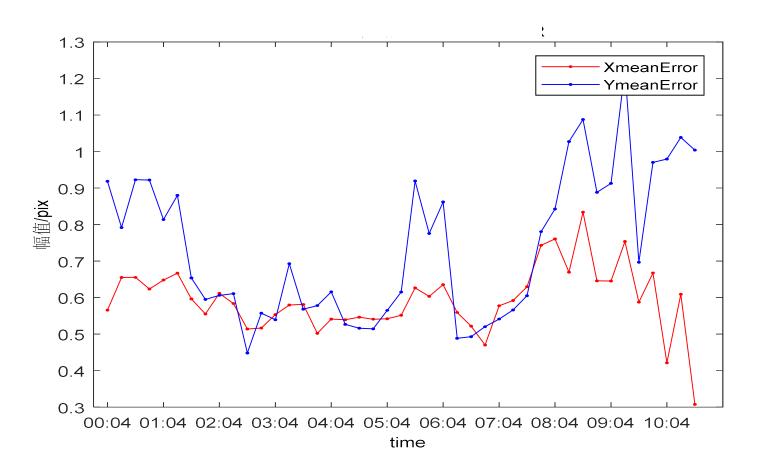


Fig.1 FY-4/LMI Prototype

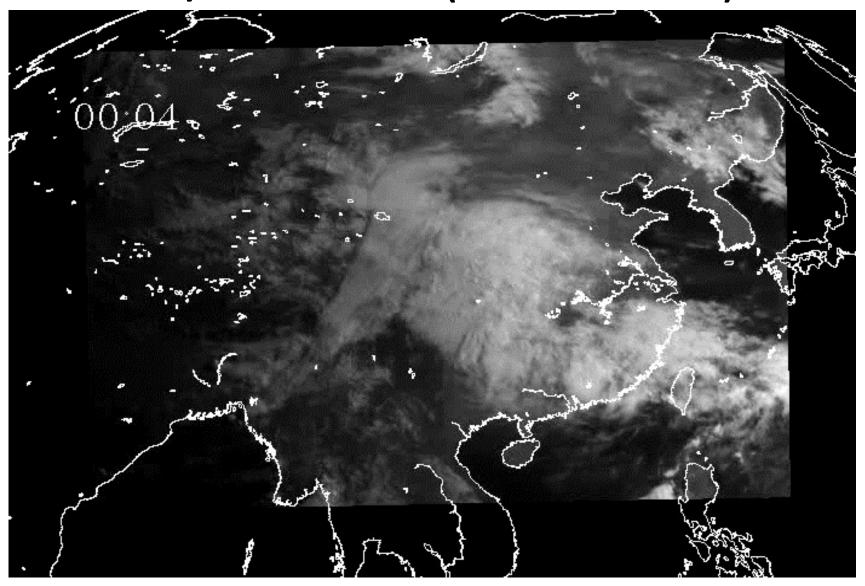
Fig.2 FY-4/LMI Spatial Coverage (7.8km@ssp)

FY-4/LMI—image navigation accuracy



20170611 FY-4A/LMI Image Navigation Performance

FY-4/LMI animation(15 mins interval)



Conclusions

- ☐ Fengyun-4 image navigation & registration algorithm and system have been developed.
- Newly updated preliminary results have revealed:
 - ✓ the imager AGRI: better than 1 IR pixel.
 - ✓ the sounder GIIRS: image navigation accuracy is better than 0.5 IR pixel and pointing variation during 16 frames is better than 0.05 IR pixel.
 - ✓ LMI: 1 pixel for the day time.
- □All the above results are in normal operations. The system performance during the eclipse, the mid-night could be worse. More on-orbit test work are needed.



Figure 1. FY-4A/AGRI and FY-2/Imager Specifications

| | FY-4A/AGRI | | FY-2/Imager | |
|-------------|----------------------|-------------------------------|--------------------|-------------------------------|
| Band No. | Wavelength (μm) | Spatial Resolution (Km) | Wavelength (μm) | Spatial Resolution (Km) |
| 1 | 0.45~0.49 | 1 | | |
| 2 | $0.55{\sim}0.75$ | 0.5 | 0.55~0.9 | 1.25 |
| 3 | 0.75~0.90 | 1 | | |
| 4 | 1.36~1.39 | 2 | | |
| 5 | 1.58~1.64 | 2 | | |
| 6 | 2.1~2.35 | 2~4 | | |
| 7 | 3.5~4.0 (high) | 2 | 3.5~4.0 | 5 |
| 8 | $3.5\sim4.0 \ (low)$ | 4 | | |
| 9 | 5.8~6.7 | 4 | 6.3~7.6 | 5 |
| 10 | 6.9~7.3 | 4 | | |
| 11 | 8.0~9.0 | 4 | | |
| 12 | 10.3~11.3 | 4 | 10.3~11.3 | 5 |
| 13 | 11.5~12.5 | 4 | 11.5~12.5 | 5 |
| 14 | 13.2~13.8 | 4 | | |